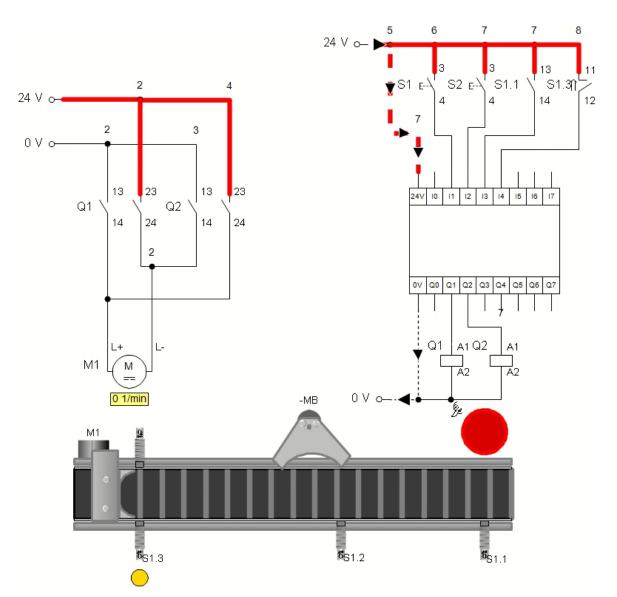
## CONTROL TECHNIK

Konsta Luomansivu

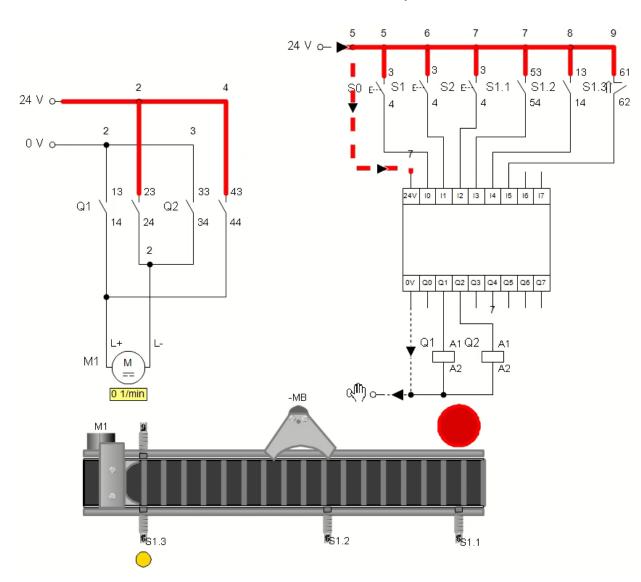
Η1

From detection of push button S1 and sensor S1.1 the conveyor drives the object to detection of S1.3. From push button S2 and sensor S1.3 the conveyor drives the object to detection of S1.1.

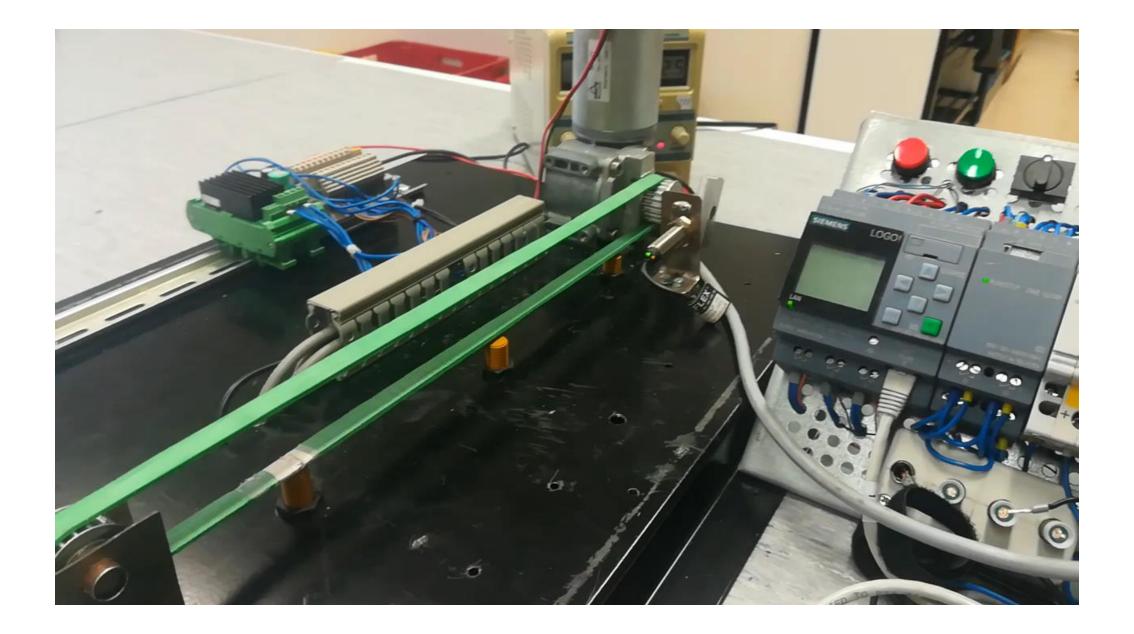




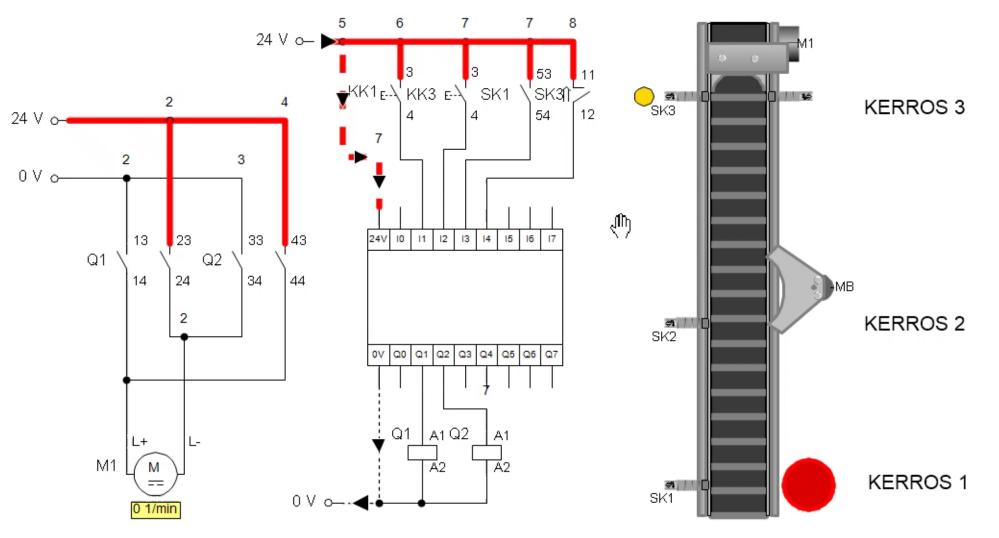
From detection of push button S1 and sensor S1.1 the conveyor drives the object to detection of S1.3. From detection of S1.3 the conveyor drives the object to detection of S1.1 and so on, so the object keeps moving back and forth from start to finish. Push button S0 stops the action.

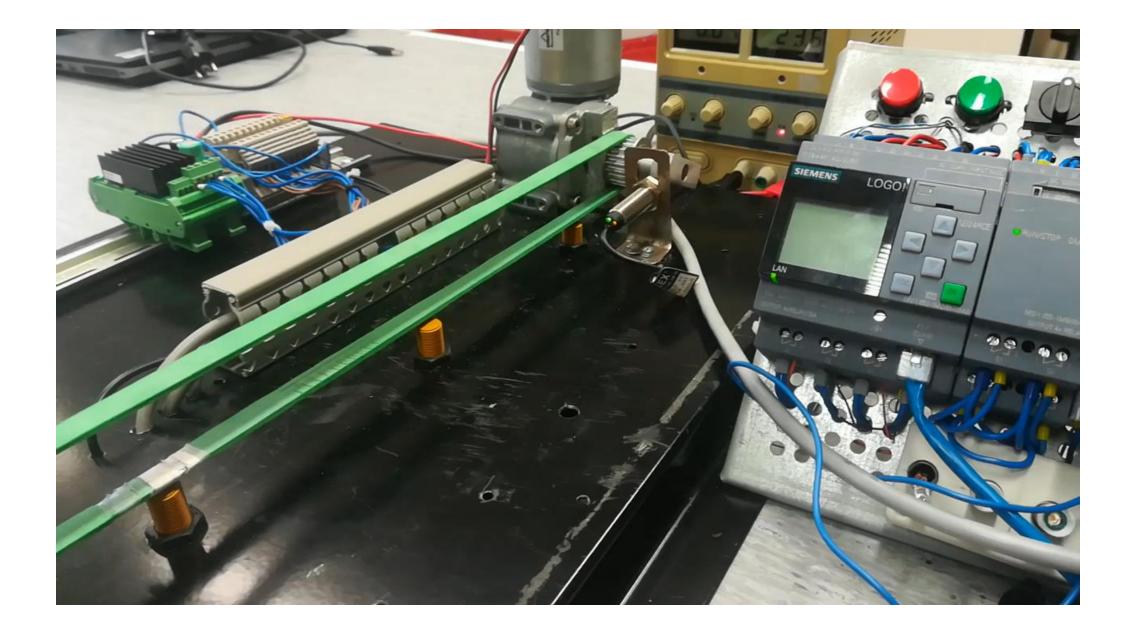


H2

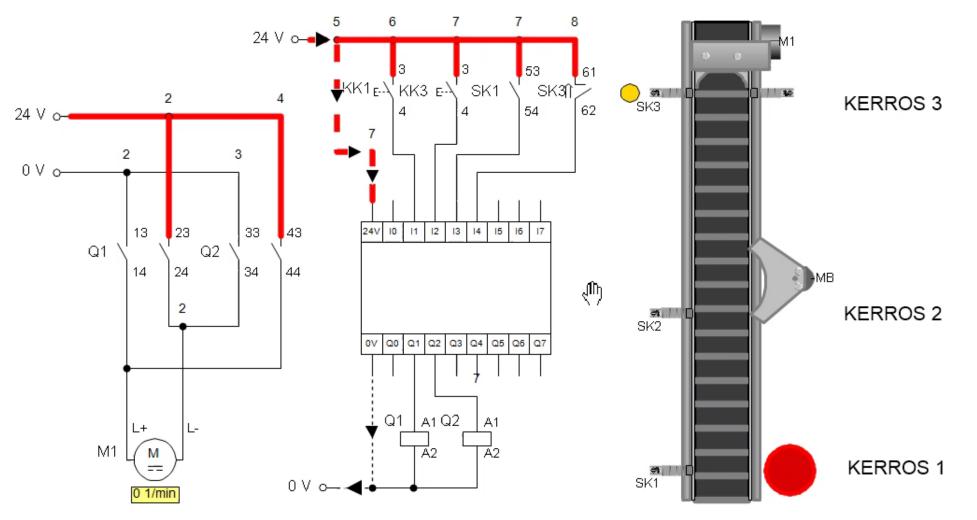


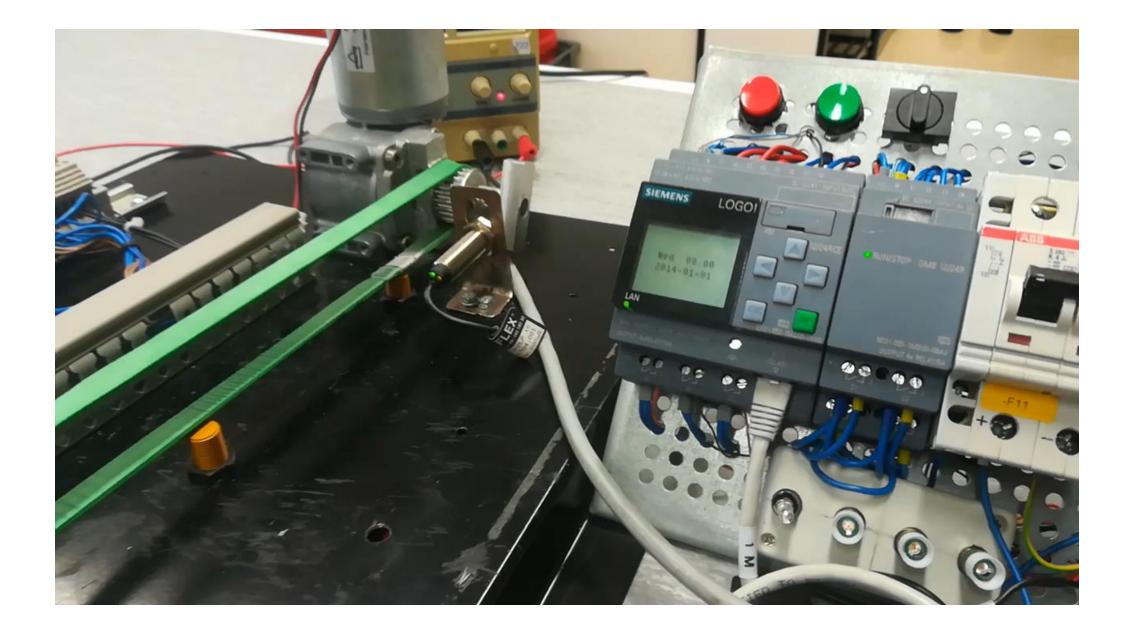
Elevator Floor 1 / Floor 3, where control is only in floor 1. Push button up brings the elevator to floor 3 and push button down brings the elevator to floor 1.



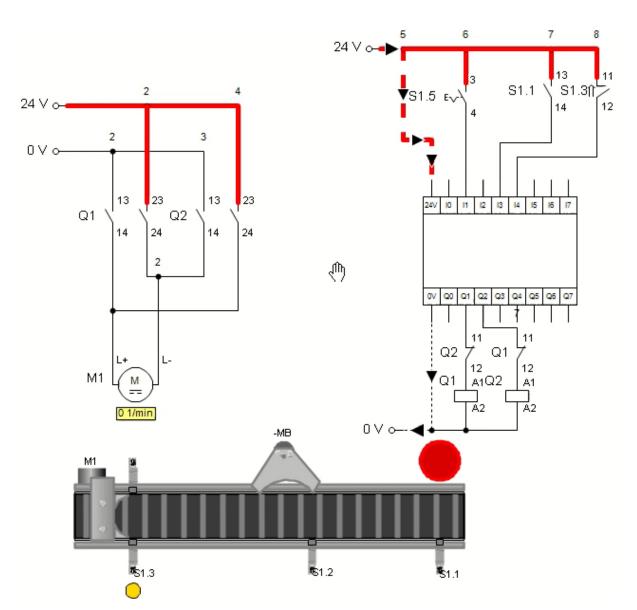


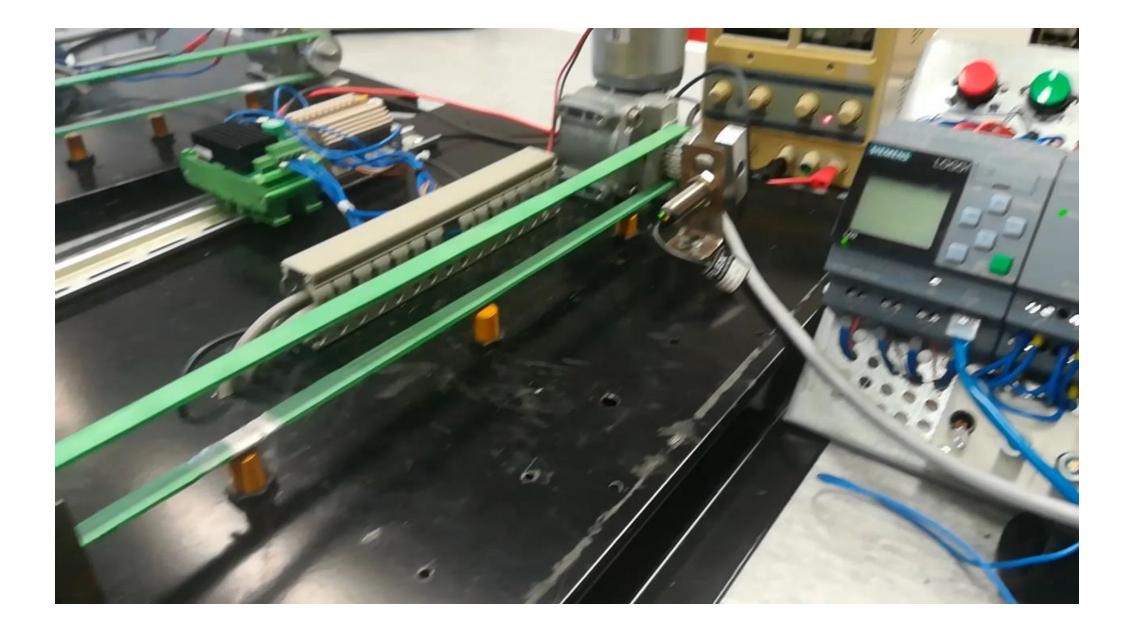
Elevator floor1 / floor3, where controls are made with one push button on both floors. First press of the push button brings the elevator to the floor and second press brings the elevator to the other floor.



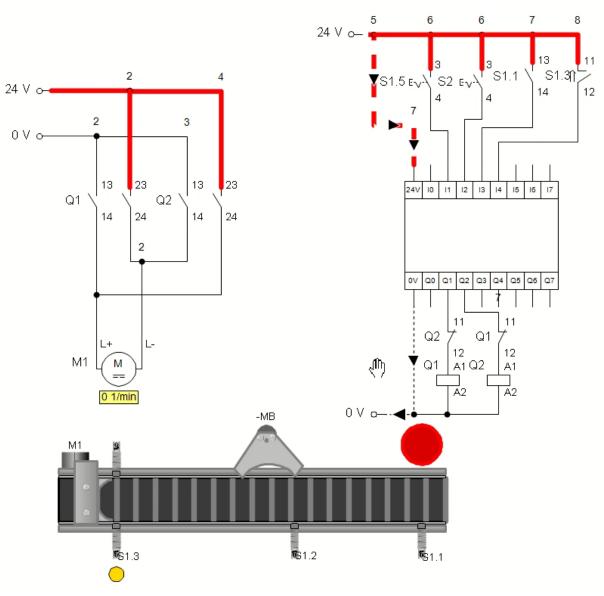


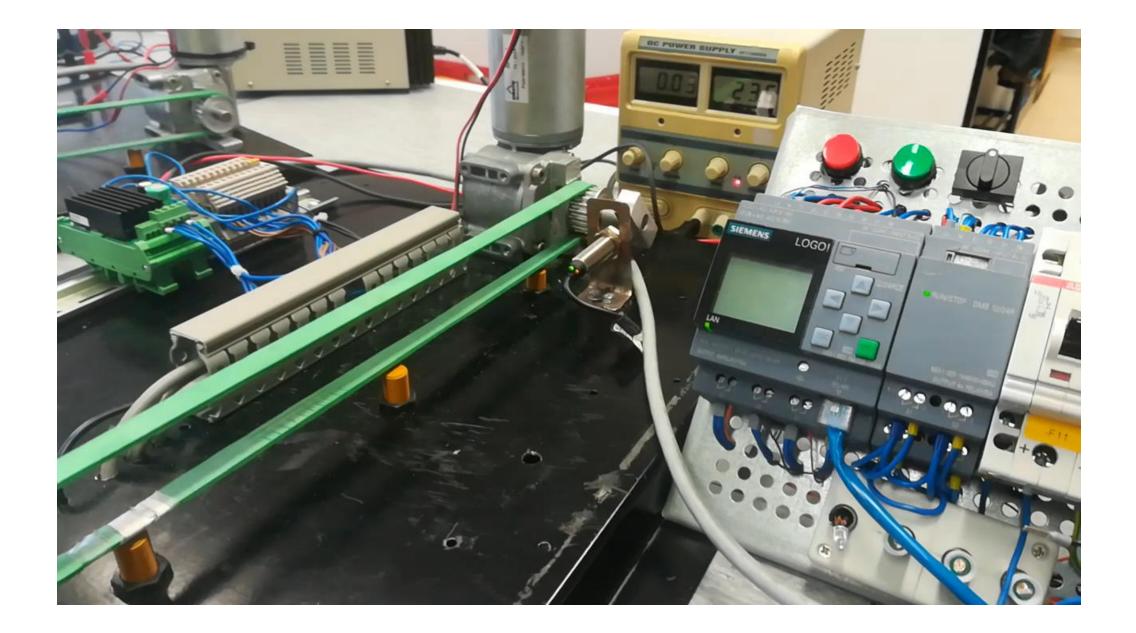
Detection of motion sensor S1.5 the port drives open and waits 5 seconds on open position, after that it closes again. This function happens only once during detection, so before next opening switch S1.5 has to open and close again.





Function is the same with H13 but RIFD-detection is added. Vehicles must therefore have to have an approved indentification card to open the port. Detection information is imported with the switch S2.





Same with H14 but safety edge function is added. So safety edge detection drives the port immediately to open position, where it waits 5 seconds and starts to close.

